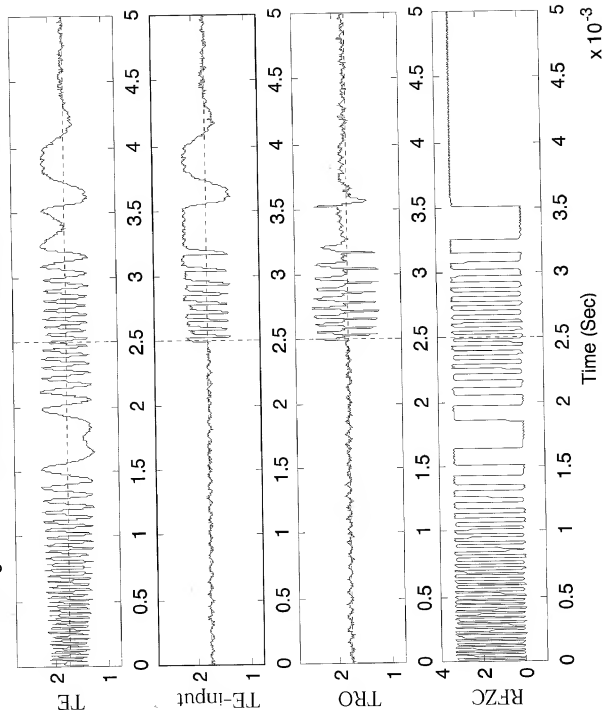


Tracking On at 16KHz, 4800RPM, use Hysteresis Operation(Prior art)

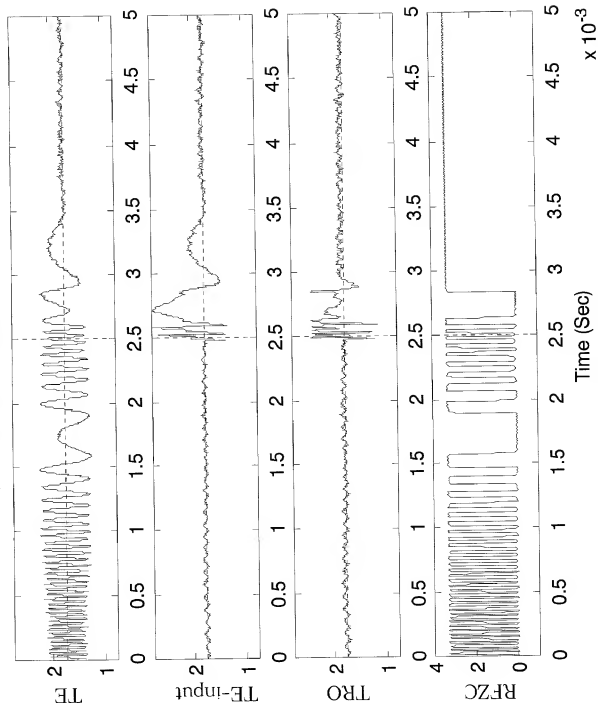


Time (Sec)

$\times 10^{-3}$

Fig. 6a

Tracking On at 16KHz, 4800RPM, use Peak Mirror



Time (Sec)

$\times 10^{-3}$

Fig. 6b